

CS F241 - MICROPROCESSOR
PROGRAMMING AND INTERFACING

DESIGN ASSIGNMENT

Group No. : 41

Question No. : 27

Made By-

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Problem Statement-

Design a microprocessor based **EPROM Programmer** to program **2716** and **2764**. The EPROM can be programmed by applying 25V at VPP and 5V at OE pin. Initially all data of EPROM will be 1's and the user should make the bits zero selectively. Before the EPROM location is programmed it must be checked for whether it is empty (data in location must be FFH if the location is empty) The 8-bit parallel data is applied to the data pins of EPROM. The address for the EPROM is to be provided. To program the address of each location to be programmed should be stable for 45ms. When address and data are stable, a 40ms active high pulse is applied to CE input. After the EPROM is programmed, IC number is to be displayed on LCD as "27xy programmed".

Assumptions Made-

- Due to limitation of the screen size of the LCD, the outputs will be shown as "27xy PROG".
- We are only using a 12-stage binary counter for convenience. In the case of programming 2764, after 2^{12} , counter will start again from zero and the circuit will work the same.
- The frequency of clock input is 200Hz and time for 1 clock is 5ms.
- The data on the data lines is FFh initially.

List of components used:

- IC 2716 - 2k EPROM
- IC 2764 - 8k EPROM
- IC 8253 - Programmable interval timer
- IC 8255 - Programmable peripheral interface
- 8086 - Intel x86 microprocessor
- 74HC4040 - 12 stage binary counter
- 74HCT138 - 3:8 decoder
- LM020L - LCD
- 74LS245 - Bidirectional Buffer

Memory Mapping:

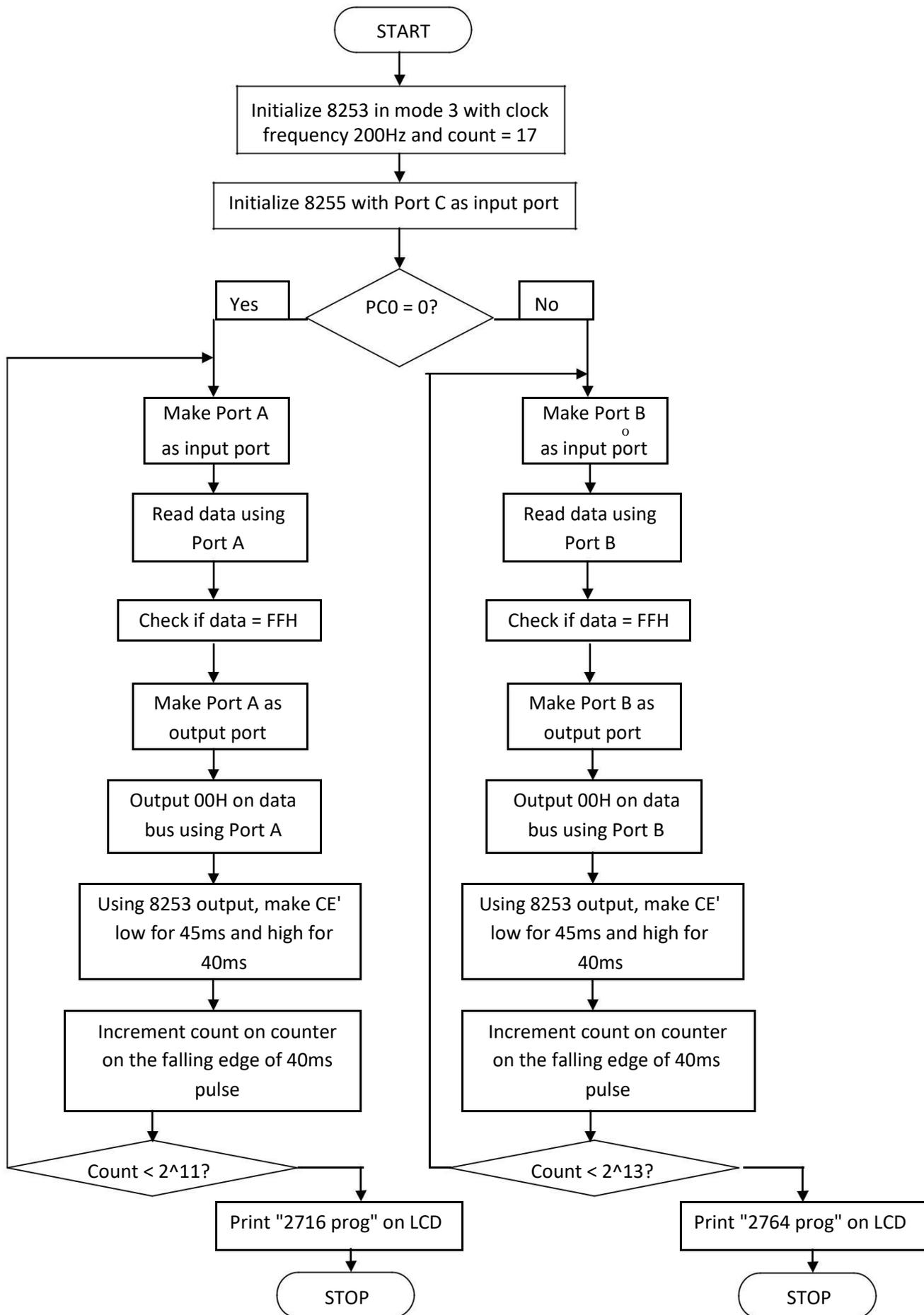
- 2716: 2000H-27FFH
- 2764: 3000H-4FFFH
- 8255: 0010H-0016H(used for interfacing LCD)
- 8255: 0008H-000EH(used for interfacing ROM)
- 8253: 0000H-0006H

Simulation:

- .asm File is created to code the above Problem Statement.
- Then, the coded file is compiled using emu Compiler.
- The generated .com file is simulated in PROTEUS Version 8.1.

NOTE: Since we are using Proteus 8.1, we can't create .dsn file but, .pdsprj format from Proteus. So, it is requested to view our files in Proteus 8.1.

Flowchart of the software-



Assembly Language Code for the project-

.model tiny

;8255 for data transfer
cr EQU 0eh ;control register
pa EQU 08h
pb EQU 0ah
pc EQU 0ch

;8255 for LCD
cr1 EQU 16h ;control register
prta EQU 10h
prtb EQU 12h
prtc EQU 14h

;8253
CR2 EQU 06h ;control register
cnt0 EQU 00h
cnt1 EQU 02h
cnt2 EQU 04h

.code
.startup

;initialising 8253
;Set to mode 3
;Counter 0 set to 17 to get 9 low pulses
;and 8 low pulses of 40 millisees each

MOV AL, 00110110b
OUT CR2, AL
MOV AL, 11h
OUT cnt0, AL
MOV AL, 00h
OUT cnt0, AL

MOV CX,0

; for 8255 1st which we use for data transaction between processor and ROM
MOV AL, 10001001b
OUT cr, AL

IN AL, pc
AND AL, 0000001B;Here we check whether C0 is set to 1 which indicates
;which ROM is being programmed
CMP AL, 00h ;If C0 is zero,ROM1 is being programmed
JZ rom1

rom2:

MOV AL, 10000010b
OUT cr, AL ;control register programmed
loop1: IN AL, pb
CMP AL,0
JE loop1 ; to ensure program stops
;till address becomes stable

CMP AL, 0ffh ;compare to see whether the location is empty i.e. all 1's
JZ x1

; Nothing done if location doesn't have FFh

x1: MOV AL, 80h
OUT cr, AL
MOV AL, 00h
OUT pb, AL
INC CX

;compare count with maxcount so that the loop can be exited if all the locations have been accessed
CMP CX,07ffh
JNZ rom2
JZ lr2

```

rom1:

MOV AL, 10010000b
OUT cr, AL
loop2 : IN AL,pa
        CMP AL,0
        JE loop2          ; to ensure program stops
                           ;till address becomes stable

CMP AL, 0ffh              ;compare to see whether the location is empty i.e. all 1's
JZ x2

; Nothing done if location doesn't have FFh

```

```

x2: MOV AL, 80h
OUT cr, AL
MOV AL, 00h
OUT pa, AL
INC CX

```

```

;compare count with maxcount so that the loop can be exited if all the locations have been accessed
CMP CX,1FFFh

```

```

JNZ rom1
JZ lr1

```

```

lr1:

```

```

;writing on the command register for initialization

```

```

CALL BEG_LCD ;calling lcd initialization
CALL RITE_2716
JMP lastcode

```

```

RITE_2716 PROC NEAR
CALL CLS
MOV AL, '2' ;display 2
CALL RITEDATA ;give to LCD
CALL DLAY ;wait before giving next character
CALL DLAY ;wait before giving next character
MOV AL, '7' ;display 7
CALL RITEDATA ;give to LCD
CALL DLAY ;wait before giving next character
CALL DLAY ;wait before giving next character
MOV AL, '1' ;display 1
CALL RITEDATA ;give to LCD
CALL DLAY ;wait before giving next character
CALL DLAY ;wait
MOV AL, '6' ;display 6
CALL RITEDATA ;give to LCD
CALL DLAY ;wait before giving next character
CALL DLAY ;wait
MOV AL, ' ' ;display space
CALL RITEDATA ;give to LCD
CALL DLAY ;wait before giving next character
CALL DLAY ;wait
MOV AL, 'P' ;display P
CALL RITEDATA ;give to LCD
CALL DLAY ;wait before giving next character
CALL DLAY ;wait
MOV AL, 'R' ;display R
CALL RITEDATA ;give to LCD
CALL DLAY ;wait before giving next character
CALL DLAY ;wait
MOV AL, 'O' ;display O
CALL RITEDATA ;give to LCD
CALL DLAY ;wait before giving next character
CALL DLAY ;wait
MOV AL, 'G' ;display G

```

```

CALL RITEDATA ;give to LCD
CALL DLAY ;wait before giving next character
CALL DLAY ;wait
RET
RITE_2716 ENDP

```

lr2:

```

;writing on the command register for initialization

```

```

CALL BEG_LCD ;calling lcd initialization
CALL RITE_2764
JMP lastcode

```

```

BEG_LCD PROC NEAR
MOV AL, 38H ;initialize LCD
CALL CORITE ;write the command to LCD
CALL DLAY ;wait before giving next command
CALL DLAY ;
CALL DLAY
MOV AL, 0EH ;send command for LCD on, cursor on
CALL CORITE
CALL DLAY
MOV AL, 01 ;clear LCD
CALL CORITE
CALL DLAY
MOV AL, 06 ;command for shifting cursor right
CALL CORITE
CALL DLAY
RET
BEG_LCD ENDP

```

```

CLS PROC
MOV AL, 01 ;clear LCD
CALL CORITE
CALL DLAY
CALL DLAY
RET
CLS ENDP

```

```

CORITE PROC ;this procedure writes commands to LCD
MOV DX, prtA
OUT DX, AL ;send the code to prt A
MOV DX, prtB
MOV AL, 00000100B ;RS=0,R/W=0,E=1 for H-To-L pulse
OUT DX, AL
NOP
NOP
MOV AL, 00000000B ;RS=0,R/W=0,E=0 for H-To-L pulse
OUT DX, AL
RET
CORITE ENDP

```

```

RITE_2764 PROC NEAR
CALL CLS
MOV AL, '2' ;display 2
CALL RITEDATA ;give to LCD
CALL DLAY ;wait before giving next character
CALL DLAY ;wait before giving next character
MOV AL, '7' ;display 7
CALL RITEDATA ;give to LCD
CALL DLAY ;wait before giving next character
CALL DLAY ;wait before giving next character
MOV AL, '6' ;display 6
CALL RITEDATA ;give to LCD
CALL DLAY ;wait before giving next character
CALL DLAY ;wait
MOV AL, '4' ;display 4
CALL RITEDATA ;give to LCD
CALL DLAY ;wait before giving next character
CALL DLAY ;wait
MOV AL, ' ' ;display space
CALL RITEDATA ;give to LCD
CALL DLAY ;wait before giving next character
CALL DLAY ;wait

```

```

MOV AL, 'P' ;display P
CALL RITEDATA ;give to LCD
CALL DLAY ;wait before giving next character
CALL DLAY ;wait
MOV AL, 'R' ;display R
CALL RITEDATA ;give to LCD
CALL DLAY ;wait before giving next character
CALL DLAY ;wait
MOV AL, 'O' ;display O
CALL RITEDATA ;give to LCD
CALL DLAY ;wait before giving next character
CALL DLAY ;wait
MOV AL, 'G' ;display G
CALL RITEDATA ;give to LCD
CALL DLAY ;wait before giving next character
CALL DLAY ;wait
RET
RITE_2764 ENDP

RITEDATA PROC
PUSH DX ;save DX
MOV DX,prtA ;DX=prt A address
OUT DX, AL ;issue the char to LCD
MOV AL, 00000101B ;RS=1, R/W=0, E=1 for H-to-L pulse
MOV DX, prtB ;prt B address
OUT DX, AL ;make enable high
MOV AL, 00000001B ;RS=1,R/W=0 and E=0 for H-to-L pulse
OUT DX, AL
POP DX
RET
RITEDATA ENDP ;writing on the lcd ends

;delay in the circuit here the delay of 20 millisecond is produced
DLAY PROC
MOV CX, 1325 ;1325*15.085 microsec = 20 msec
W1:
NOP
NOP
NOP
NOP
NOP
LOOP W1
RET
DLAY ENDP

lastcode: NOP

.exit
END

```
