

DETAILED DESCRIPTION

Operation

The TPS61042 operates like a standard boost converter but regulates the voltage across the sense resistor (R_S) instead of the output voltage. This gives an accurate regulated LED current independent of the input voltage and number of LEDs connected. With integrated overvoltage protection (OVP) the TPS61042 is configured as a current source with overvoltage protection ideally suited to drive LEDs. With the 30V internal switch, the device can generate output voltages of up to 27.5 V and has an internal 500mA MOSFET switch (Q1). This allows several LEDs to be connected in series to the output. The internal LED switch (Q2) in series with the LEDs has a maximum current rating of 60 mA and disconnects the LEDs from ground during shutdown. The LED switch is driven by a PWM signal applied to the control pin (CTRL), which directly controls the LED brightness. With this control method the LED brightness depends on the PWM duty cycle only and is independent of the PWM frequency and amplitude.

Boost Converter

The boost converter operates in a pulse frequency modulation (PFM) scheme with constant peak current control. This control scheme maintains high efficiency over the entire load current range and with a switching frequency of up to 1 MHz, enables the use of small external components. The converter monitors the sense voltage across R_S with the feedback pin (FB) and, when the feedback voltage falls below the reference voltage (252 mV typ), the main switch turns on and the current ramps up. The main switch turns off when the inductor current reaches the internally set peak current of 500 mA (typ). Refer to the *peak current control* section for more information. The second criteria that turns off the main switch is the maximum on-time of 6 μ s (typ). This limits the maximum on-time of the converter in extreme conditions. As the switch is turned off the external Schottky diode is forward biased, delivering the stored inductor energy to the output. The main switch remains off until the minimum off time of 400 ns (typ) has passed and the feedback voltage is below the reference voltage again. Using this PFM peak current control scheme, the converter operates in discontinuous conduction mode (DCM) where the switching frequency depends on the inductor, input and output voltage, and LED current. Lower LED currents reduce the switching frequency, which results in high efficiency over the entire LED current range. This regulation scheme is inherently stable, allowing a wide range for the selection of the inductor and output capacitor.

Peak Current Control (Boost Converter)

The internal switch is turned on until the inductor current reaches the DC current limit (I_{LIM}) of 500 mA (typ) . Due to the internal current limit delay of 100 ns (typ) the actual current exceeds the DC current limit threshold by a small amount. The typical peak current limit can be calculated:

$$I_{P(typ)} = I_{(LIM)} + \frac{V_I}{L} \times 100 \text{ ns}$$

$$I_{P(typ)} = 500 \text{ mA} + \frac{V_I}{L} \times 100 \text{ ns}$$

The higher the input voltage and the lower the inductor value, the greater the current limit overshoot.

Softstart

All inductive step-up converters exhibit high in-rush current during start-up if no special precautions are taken. This can cause voltage drops at the input rail during start-up, which may result in an unwanted or premature system shutdown.

The TPS61042 limits this in-rush current during start-up by increasing the current limit in two steps starting from $I_{LIM}/4$ for 256 switch cycles to $I_{LIM}/2$ for the next 256 switch cycles and then full current limit. See [Figure 12](#) for typical start-up behavior.

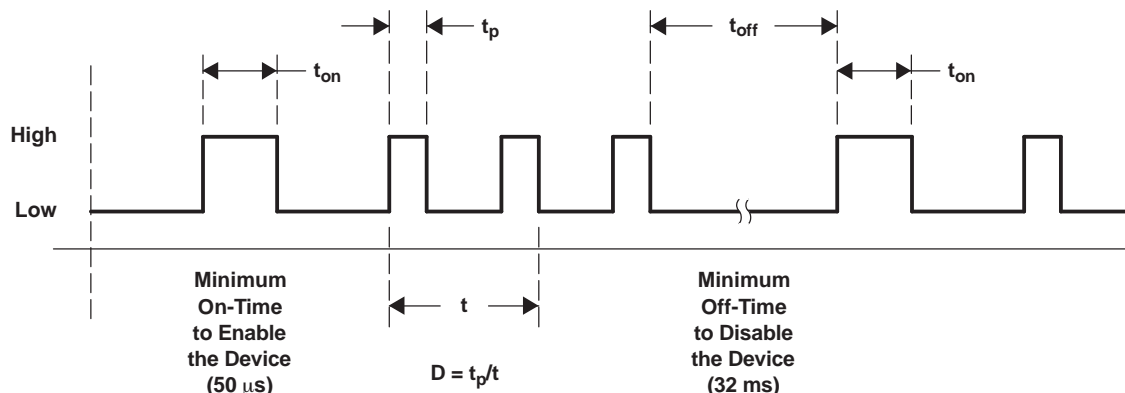
DETAILED DESCRIPTION (continued)**Control (CTRL)**

The CTRL pin serves two functions. One is the enable and disable of the device. The other is the PWM control of the internal LED switch (Q2). If no PWM signal is applied to the CTRL pin, then the CTRL pin can be used as a standard enable pin for the device. To enable the device, the CTRL pin must be pulled high for time period of at least 50 μ s. The device starts with the Softstart cycle. Pulling the CTRL pin to GND for a time period ≥ 32 ms disables the device, disconnecting the LEDs from GND by opening the LED switch (Q2) to avoid any LED leakage current. See [Figure 16](#) for the CTRL pin timing.

The internal LED switch (Q2) is driven by the PWM signal when applied to the CTRL pin. Applying a PWM signal in the range of 100 Hz to 50 kHz allows the LED current to be pulsed with the duty cycle of the PWM signal. The CTRL pin accepts a PWM duty cycle from $D = 1\%$ to 100%. Duty cycles below 1% are also possible with the restriction that the device is forced into shutdown as the off time of the applied PWM signal exceeds 10 ms.

When a PWM signal is applied to the CTRL pin the LED switch (Q2) turns on immediately. The internal error comparator is disabled for 400 ns. This 400 ns delay time is required to establish the correct voltage level across the sense resistor R_S after the LED switch (Q2) is closed.

To achieve good LED current accuracy and linearity, the switching frequency of the converter must be higher than the PWM frequency applied to the CTRL pin.

**Figure 16. CTRL Timing Diagram**

The CTRL timing diagram is shown in [Figure 16](#). To enable the device, the CTRL signal must be high for 50 μ s. The PWM signal can then be applied with a pulse width (t_p) greater or smaller than t_{ON} . To force the device into shutdown mode, the CTRL signal must be low for at least 32 ms. Requiring the CTRL pin to be low for 32ms before the device enters shutdown allows for PWM dimming frequencies as low as 100 Hz. The device is enabled again when a CTRL signal is high for a period of 50 μ s minimum. See [Figure 11](#) for the PWM duty cycle versus LED current characteristic.

This CTRL pin must be terminated.

Applying a PWM Signal to the CTRL Pin with an On-Time $t_p \leq 2.5\mu$ s

In such a case the on-time of the PWM signal, t_p , must be $> 2.5\mu$ s until the softstart is completed. The softstart is completed after 512 switching cycles. To simply, estimate the softstart time, multiply the period of the PWM signal times 512, and add 50 μ s to it. For a 50-kHz signal this would be 10.3ms as a minimum softstart time period. After the softstart time is completed the PWM on time can be reduced to $t_p > 400$ ns.

DETAILED DESCRIPTION (continued)**Overvoltage Protection (OVP)**

As with any current source, the output voltage rises as the output impedance increases or is disconnected. To prevent the output voltage from exceeding the maximum main switch (Q1) voltage rating of 30 V, an overvoltage protection circuit is integrated. When the output voltage exceeds the OVP threshold voltage, (Q1) turns off. The converter switch remains off until the output voltage falls below the OVP threshold voltage. As long as the output voltage is below the OVP threshold the converter continues its normal operation, until the output voltage exceeds the OVP threshold again.

Undervoltage Lockout

An undervoltage lockout feature prevents mis-operation of the device at input voltages below 1.5 V (typ). As long as the input voltage is below the undervoltage threshold the device remains off, with the main MOSFET switch (Q1) and the LED switch (Q2) open.

Thermal Shutdown

An internal thermal shutdown is implemented in the TPS61042 that shuts down the device if the typical junction temperature of 160°C is exceeded. If the device is in thermal shutdown mode, the main MOSFET switch (Q1) and the LED switch (Q2) are open.

APPLICATION INFORMATION

Inductor Selection, Maximum Load Current, and Switching Frequency

The PFM peak current control scheme of the TPS61042 is inherently stable. The inductor value does not affect the stability of the regulator. The selection of the inductor together with the nominal LED current, input, and output voltage of the application determines the switching frequency of the converter.

The first step is to calculate the maximum load current the converter can support using the selected inductor. The inductor value has less effect on the maximum available load current and is only of secondary order. A good inductor value to start with is 4.7 μH . Depending on the application, inductor values down to 1.0 μH can be used. The maximum inductor value is determined by the maximum on time of the switch of 6 μs (typ). The peak current limit of 500 mA (typ) must be reached within this 6 μs for proper operation. The maximum load current of the converter is determined at the operation point where the converter starts to enter the continuous conduction mode. The converter must always operate in discontinuous conduction mode to maintain regulation.

Depending on the time period of the inductor current fall time being larger or smaller compared to the minimum off time of the converter (400ns typ), the maximum load current can be calculated.

Inductor fall time:

$$t_{\text{fall}} = \frac{i_p \times L}{V_{\text{out}} - V_{\text{in}}}$$

For $t_{\text{fall}} \geq 400 \text{ ns}$

$$I_{\text{load max}} = \eta \frac{i_p \times V_{\text{in}}}{2 \times V_{\text{out}}}$$

for $t_{\text{fall}} \leq 400 \text{ ns}$

$$I_{\text{load max}} = \eta \times \frac{i_p^2 \times L \times V_{\text{in}}}{(V_{\text{out}} - V_{\text{in}}) \times (2 \times i_p \times L + 2 \times 400 \text{ ns} \times V_{\text{in}})}$$

with:

L = selected inductor value

η = expected converter efficiency. Typically between 70% to 85%

$$i_p = 500 \text{ mA} + \frac{V_{\text{in}}}{L} \times 100 \text{ ns}$$

(Peak inductor current as described in the *peak current control* section)

The above formula contains the expected converter efficiency that allows calculating the expected maximum load current the converter can support. The efficiency can be taken out of the efficiency graphs shown in [Figure 2](#) and [Figure 3](#) or 80% can be used as an accurate estimation.

If the converter can support the desired LED current, the next step is to calculate the converter switching frequency at the operation point, which must be $\leq 1 \text{ MHz}$. Also the converter switching frequency should be much higher than the applied PWM frequency at the CTRL pin to avoid non-linear brightness control. Assuming the converter shows no double pulses or pulse bursts ([Figure 13](#), [Figure 14](#)) on the switch node (SW) the switching frequency at the operation point can be calculated as:

$$f_{\text{s(ILOAD)}} = \frac{2 \times I_{\text{LOAD}} \times (V_{\text{O}} - V_{\text{I}} + V_{\text{F}})}{\left(I_{\text{(LIM)}} + \frac{V_{\text{in}}}{L} \times 100 \text{ ns} \right)^2 \times L}$$

with:

$I_{\text{(LIM)}}$ = minimum switch current limit (500 mA typ)

L = selected inductor value

$I_{\text{(LOAD)}}$ = nominal load or LED current

V_{F} = Rectifier diode forward voltage (typically 0.3 V)

APPLICATION INFORMATION (continued)

The smaller the inductor value, the higher the switching frequency of the converter but the lower the efficiency.

The selected inductor must have a saturation current that meets the maximum peak current of the converter as calculated in the *peak current control* section. Use the maximum value for $I_{(LIM)}$ (600mA) for this calculation.

Another important inductor parameter is the DC resistance. The lower the DC resistance the higher the efficiency of the converter. See [Table 1](#) and [Figure 22](#) to [Figure 27](#) for inductor selection.

Table 1. Possible Inductor

Inductor Value	Component Supplier	Size
10 μ H	muRata LQH43CN100K01	4,5 mm×3,2 mm×2,6 mm
4.7 μ H	muRata LQH32CN4R7M11	3,2 mm×2,5 mm×2,0 mm
10 μ H	Coilcraft DO1605T-103MX	5,5 mm ×4,1 mm ×1,8 mm
4.7 μ H	Sumida CDRH3D16-4R7	3,8 mm×3,8 mm×1,8 mm
3.3 μ H	Sumida CMD4D11- 3R3	3,5 mm×5,3 mm×1,2 mm
4.7 μ H	Sumida CMD4D11- 4R7	3,5 mm×5,3 mm×1,2 mm
3.3 μ H	Sumida CMD4D11- 3R3	3,5 mm×5,3 mm×1,2 mm
4.7 μ H	Coiltronics SD12-4R7	5,2 mm×5,2 mm×1,2 mm
3.3 μ H	Coilcraft LPO1704-332M	6,6 mm×5,5 mm×1,0 mm
4.7 μ H	Coilcraft LPO1704-472M	6,6 mm×5,5 mm×1,0 mm

Output Capacitor Selection and Line Regulation

For better output voltage filtering, a low ESR output capacitor is recommended. Ceramic capacitors have a low ESR value, but depending on the application, tantalum capacitors can be used.

The selection of the output capacitor value directly influences the output voltage ripple of the converter which also influences line regulation. The larger the output voltage ripple, the larger the line regulation, which means that the LED current changes if the input voltage changes. If a certain change in LED current gives a noticeable change in LED brightness, depends on the LED manufacturer and on the application. Applications requiring good line regulation $\leq 1\%/V$ (typ) must use output capacitor values $\geq 1 \mu$ F.

See [Table 2](#) and [Figure 22](#) to [Figure 27](#) for the selection of the output capacitor.

Assuming the converter does not show double pulses or pulse bursts on the switch node (SW), the output voltage ripple is calculated as (see [Figure 13](#), [Figure 14](#)):

$$\Delta V_O = \frac{I_O}{C_O} \times \left[\frac{1}{f_{s(ILOAD)}} - \frac{\left(I_{(LIM)} + \frac{V_{in}}{L} \times 100 \text{ ns} \right) \times L}{V_O + V_F - V_I} \right] + I_P \times \text{ESR}$$

with:

$I_{(LIM)}$ = minimum switch current limit (400 mA typ)

L = selected inductor value

$I_{(LOAD)}$ = nominal load current

f_s = switching frequency at the nominal load current as calculated before.

V_F = rectifier diode forward voltage (0.3 V typ)

C_O = selected output capacitor

ESR = output capacitor ESR value

Input Capacitor Selection

For good input voltage filtering, low ESR ceramic capacitors are recommended. A 4.7 µF ceramic input capacitor is sufficient for most applications. For better input voltage filtering the capacitor value can be increased. Refer to Table 2 and [Figure 22](#) to [Figure 27](#) for input capacitor selection.

Table 2. Possible Input and Output Capacitors

Capacitor	Voltage rating	Component Supplier	Comments
4.7 µF/X5R/0805	6.3 V	Tayo Yuden JMK212BY475MG	C _I
10 µF/X5R/0805	6.3 V	Tayo Yuden JMK212BJ106MG	C _I
100 nF		Any	C _O
220 nF		Any	C _O
470 nF		Any	C _O
1.0 µF/X7R/1206	25 V	Tayo Yuden TMK316BJ105KL	C _O
1.0 µF/X7R/1206	35 V	Tayo Yuden GMK316BJ105KL	C _O
4.7 µF/X5R/1210	25 V	Tayo Yuden TMK325BJ475MG	C _O

Diode Selection

To achieve high efficiency, a Schottky diode must be used. The current rating of the diode must meet the peak current rating of the converter as it is calculated in the *peak current control* section. Use the maximum value for I_(Lim) for this calculation. See [Table 3](#) and [Figure 22](#) to [Figure 27](#) for the Schottky diode selection.

Table 3. Possible Diodes

Component Supplier	Reverse voltage
ON Semiconductor MBR0530	30 V
ON Semiconductor MBR0520	20 V
Toshiba CRS02	30 V
Zetex ZHCS400	40 V

Efficiency

The overall efficiency of the application depends on the specific application conditions and mainly on the selection of the inductor. A lower inductor value increases the switching frequency and switching losses yielding in a lower efficiency. A lower inductor dc resistance has lower copper losses, giving a higher efficiency. Therefore, the efficiency can typically vary ±5% depending on the selected inductor. [Figure 2](#) and [Figure 3](#) can be used as a guideline for the application efficiency. These curves show the typical efficiency powering four LEDs using a 4.7 µH inductor with just 1,2 mm height. The efficiency curve in [Figure 2](#) and [Figure 3](#) show the efficiency delivering the power to the LEDs rather than the overall converter efficiency and is calculated as:

$$\eta = \frac{V_{LED} \times I_{LED}}{V_I \times I_I}$$

Setting The LED Current

The converter regulates the LED current by regulating the voltage across the current sense resistor (R_S). The voltage across the sense resistor is regulated to the internal reference voltage of $V_{(FB)} = 252 \text{ mV}$.

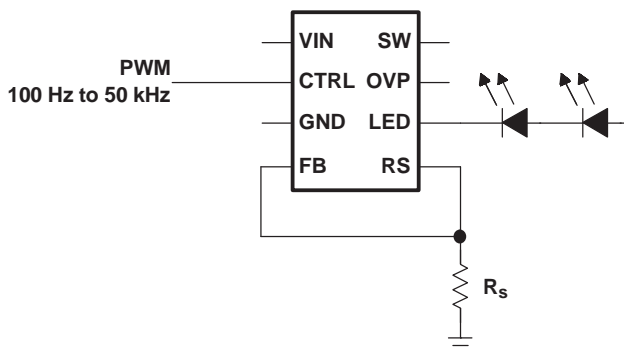


Figure 17. Setting the LED Current

The LED current can be calculated:

$$I_{LED} = \frac{V_{FB}}{R_S} = \frac{0.252 \text{ V}}{R_S}$$

The current programming method is used when the brightness of the LEDs is fixed or controlled by a PWM signal applied to the CTRL pin. When using a PWM signal on the CTRL pin, the LED brightness is only dependent on the PWM duty cycle, independent of the PWM frequency, or amplitude, which simplifies the system.

Alternatively, an analog voltage can be used as well to control the LED brightness.

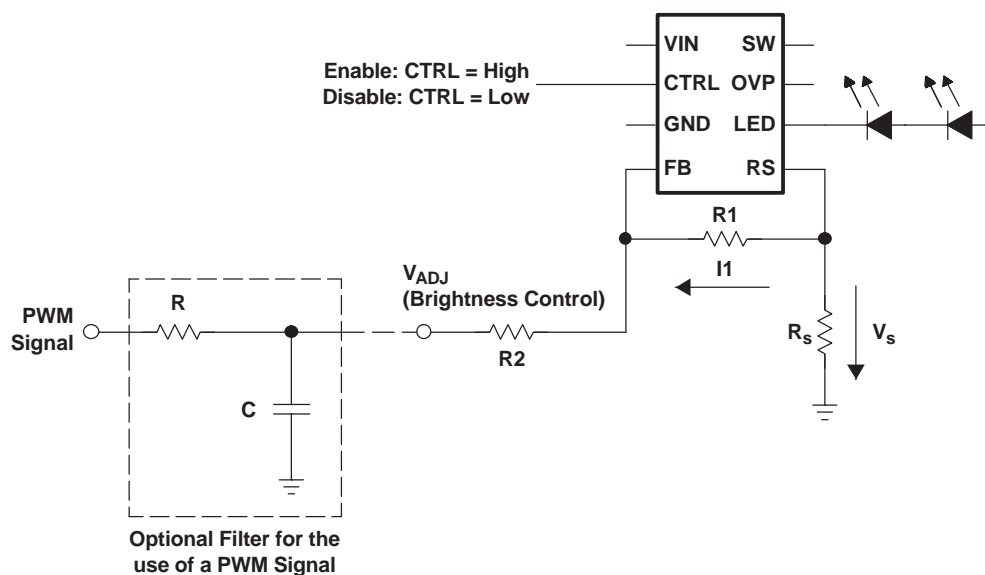


Figure 18. Setting the LED Current

In [Figure 18](#) the LED current is determined by the voltage applied to R2 ($V_{(adj)}$) and the selection of R1, R2 and the sense resistor (R_S). In this configuration, the LED current is linear controlled instead of pulsed as in the configuration before. To select the resistor values following steps are required.

1. Select the voltage $V_{(adjmax)}$ to turn the LEDs off. $\rightarrow V_{(adjmax)}$ (e.g. 3.3 V)
2. Select the voltage $V_{(adjmin)}$ to turn the LEDs fully on. $\rightarrow V_{(adjmin)}$ (e.g. 0.0 V)
3. Select the maximum and minimum LED current $I_{O(max)}$ and $I_{O(min)}$. \rightarrow (e.g. $I_{O(max)} = 20 \text{ mA}$, $I_{O(min)} = 0 \text{ mA}$)
4. Calculate R2 to achieve a feedback current in the range of $I_1 = 3 \text{ }\mu\text{A}$ to $10 \text{ }\mu\text{A}$ as the LEDs are fully turned on:

$$R2 = \frac{V_{ref} - V_{adj(min)}}{I_1}$$

5. Calculation of R1

$$R1 = V_{ref} \times \frac{I_{O(max)} \times R2 + V_{adj(min)} - I_{O(min)} \times R2 - V_{adj(max)}}{V_{adj(max)} \times I_{O(max)} + V_{ref} \times I_{O(min)} - V_{adj(min)} \times I_{O(min)} - V_{ref} \times I_{O(max)}}$$

6. Calculation of the sense voltage (V_S) at maximum LED current

$$V_S = V_{ref} \times \left(1 + \frac{R1}{R2}\right) - \frac{R1}{R2} \times V_{adj(min)}$$

7. Calculation of the required sense resistor (R_S)

$$R_S = \frac{V_S}{I_{O(max)}}$$

PWM Control With Separate Enable

The control pin (CTRL) combines the enable function as well as the PWM brightness control function in one pin. For some systems an independent enable function is required. One way to implement this is to use the brightness control configuration as shown in the previous section [Figure 18](#).

Other possible solutions are shown in [Figure 19](#), [Figure 20](#), [Figure 21](#).

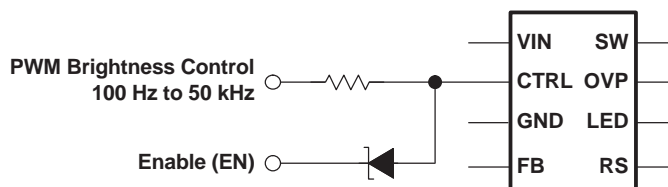


Figure 19. Separate Enable and PWM Control Using a Schottky Diode

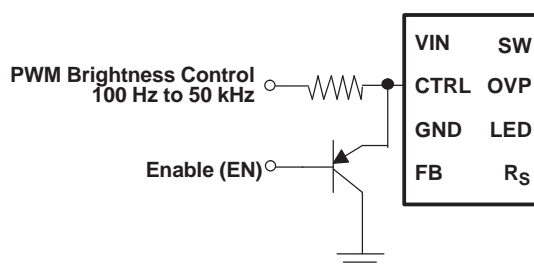


Figure 20. Separate Enable and PWM Control Using a Transistor

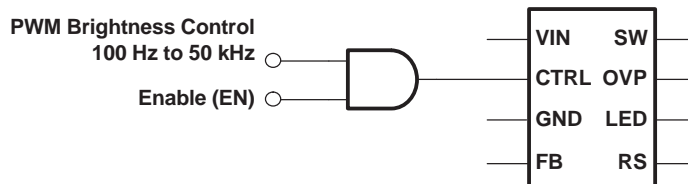


Figure 21. Separate Enable and PWM Control Using an AND Gate

Layout Considerations

In all switching power supplies the layout is an important step in the design, especially at high peak currents and switching frequencies. If the layout is not carefully done, the regulator might show noise problems and duty cycle jitter.

The input capacitor should be placed as close as possible to the input pin for good input voltage filtering. The inductor and diode must be placed as close as possible to the switch pin to minimize noise coupling into other circuits. Since the feedback pin and network is a high impedance circuit, the feedback network should be routed away from the inductor.

Thermal Considerations

The TPS61042 comes in a thermally enhanced QFN package. The package includes a thermal pad improving the thermal capabilities of the package. See the QFN/SON PCB Attachment application note (SLUA271).

The thermal resistance junction to ambient $R_{\theta JA}$ of the QFN package greatly depends on the PCB layout. Using thermal vias and wide PCB traces improves the thermal resistance $R_{\theta JA}$. Under normal operation conditions no PCB vias are required for the thermal pad. However, the thermal pad must be soldered to the PCB.

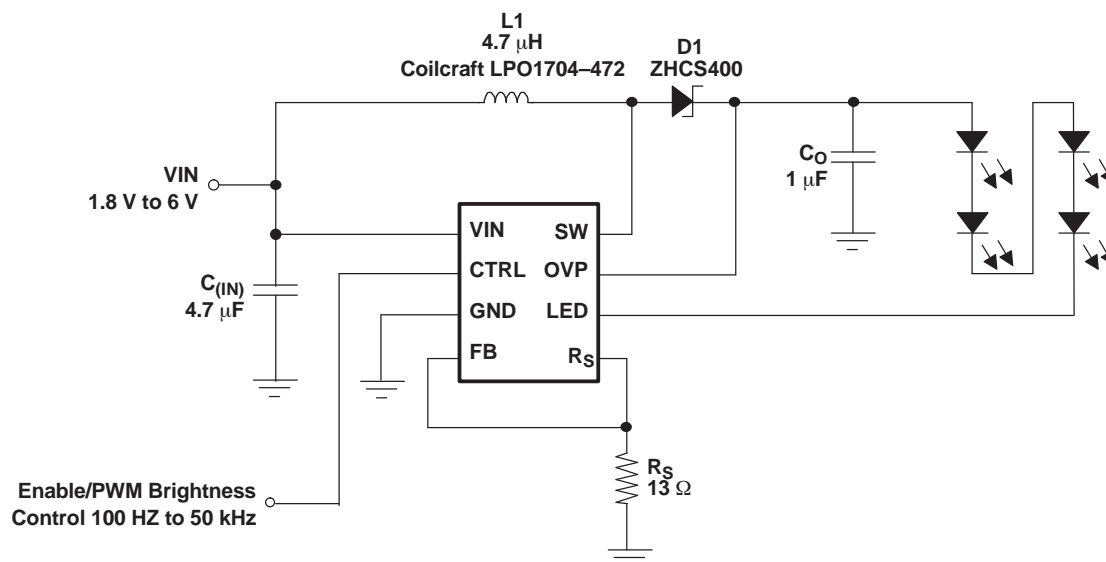


Figure 22. TPS61042 With 1,0 mm Total System Height. Efficiency = 82.7% @ $V_I = 3.0$ V/19 mA

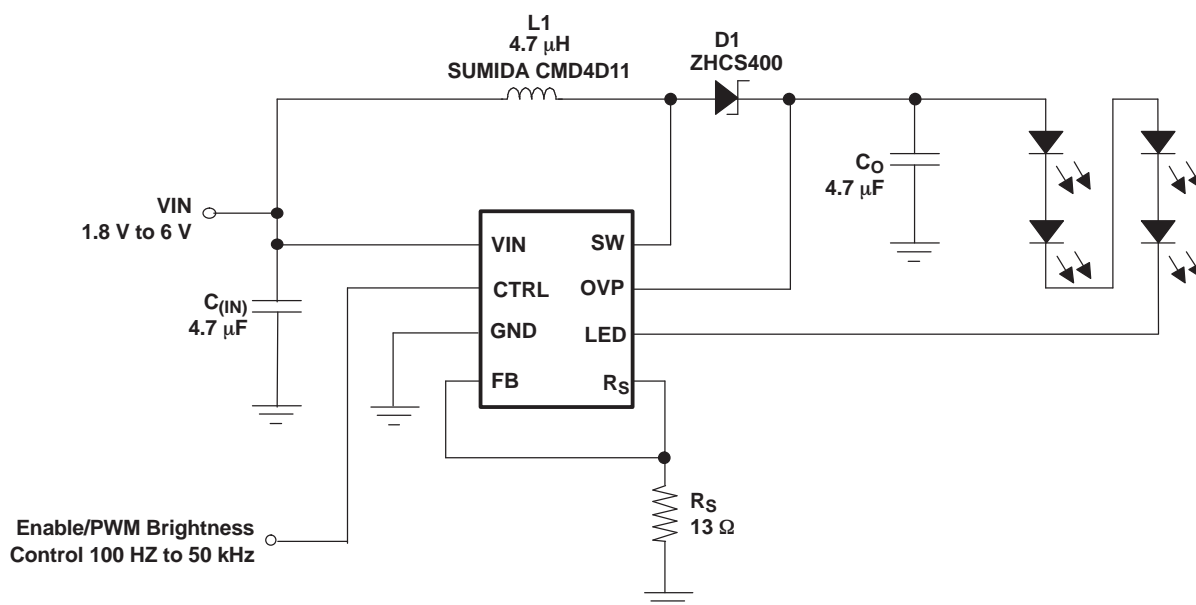


Figure 23. TPS61042 With Low LED Ripple Current and Higher Accuracy Using a 4.7 μF Output Capacitor

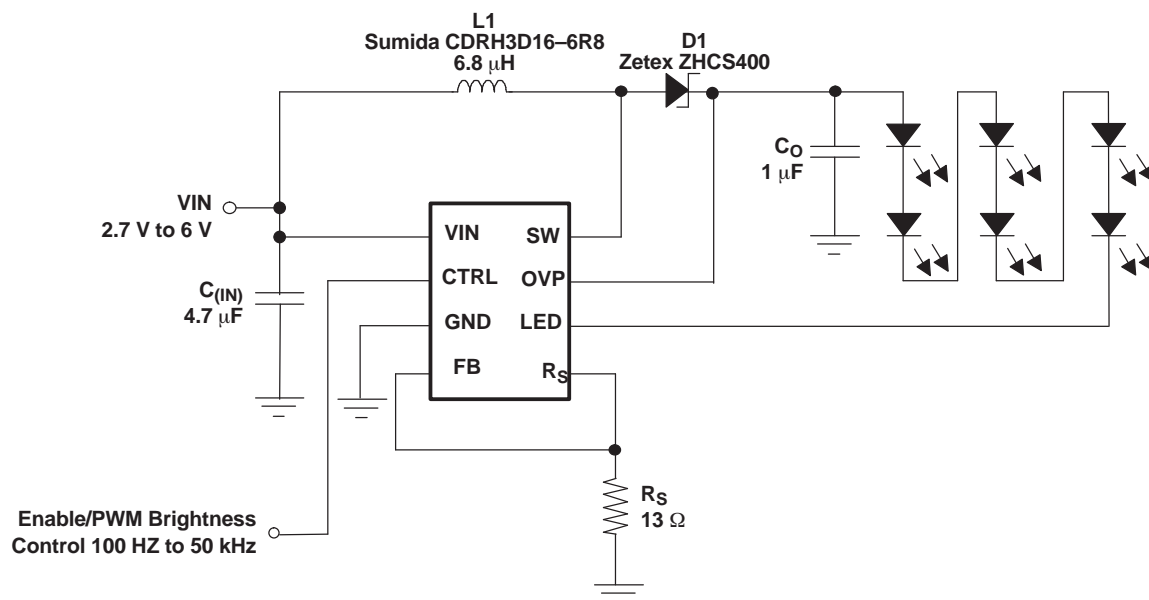


Figure 24. TPS61042 Powering 6 LEDs, Efficiency = 84% @ $V_I = 3.6\text{ V}/19\text{ mA}$

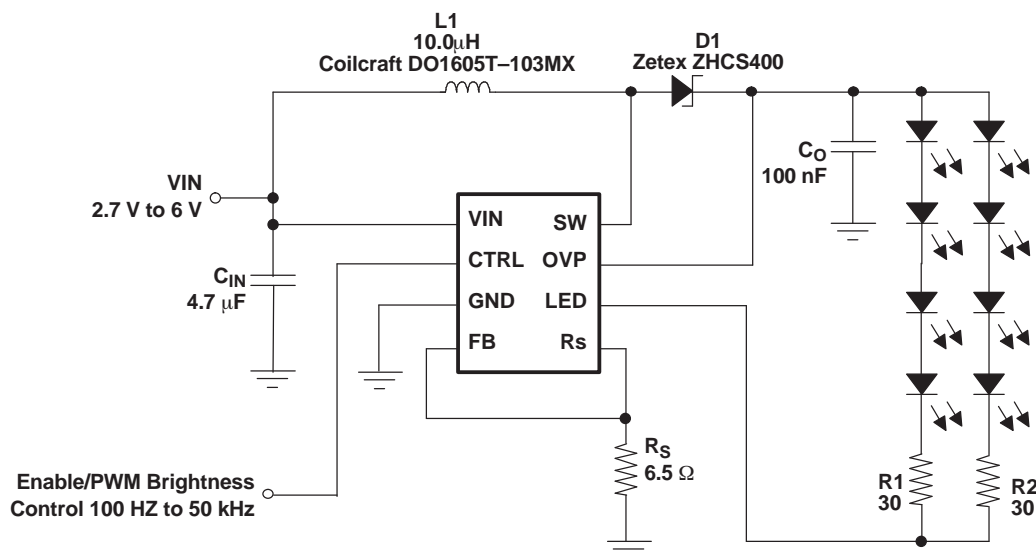


Figure 25. TPS61042 Powering 8 LEDs, Efficiency = 81% @ $V_I = 3.6\text{ V}/18.6\text{ mA}$

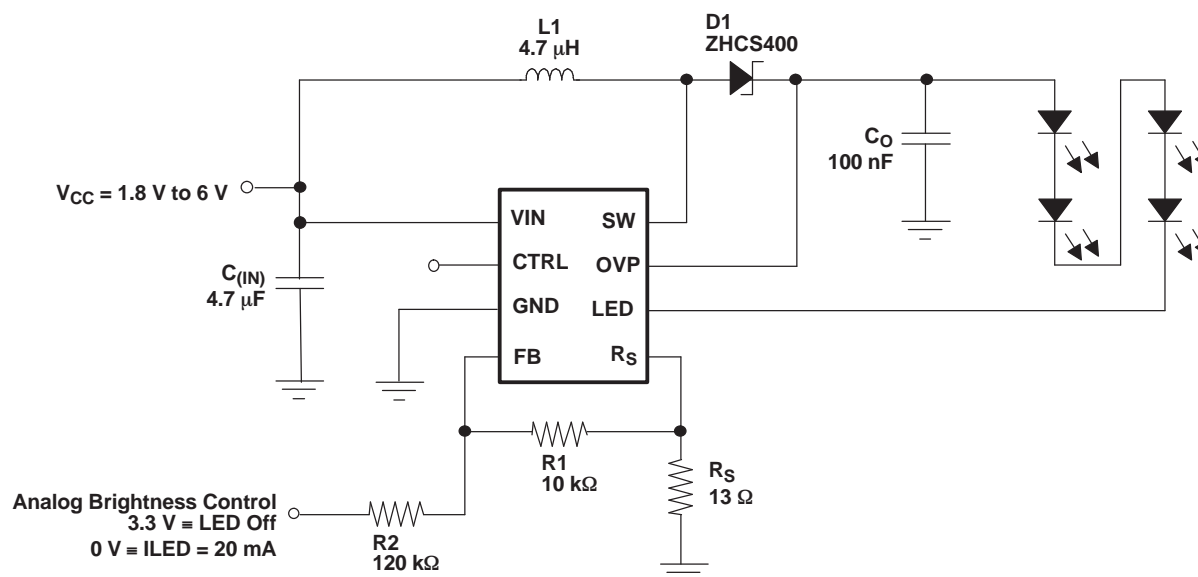


Figure 26. Adjustable Brightness Control Using an Analog Voltage

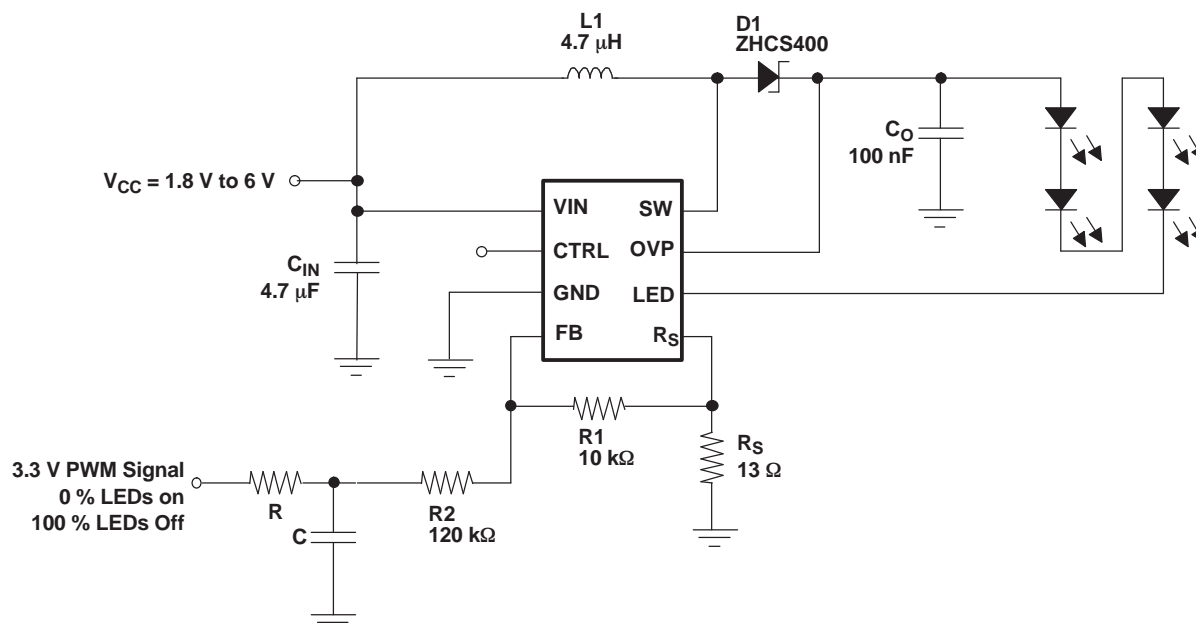


Figure 27. Alternative Adjustable Brightness Control Using PWM Signal